

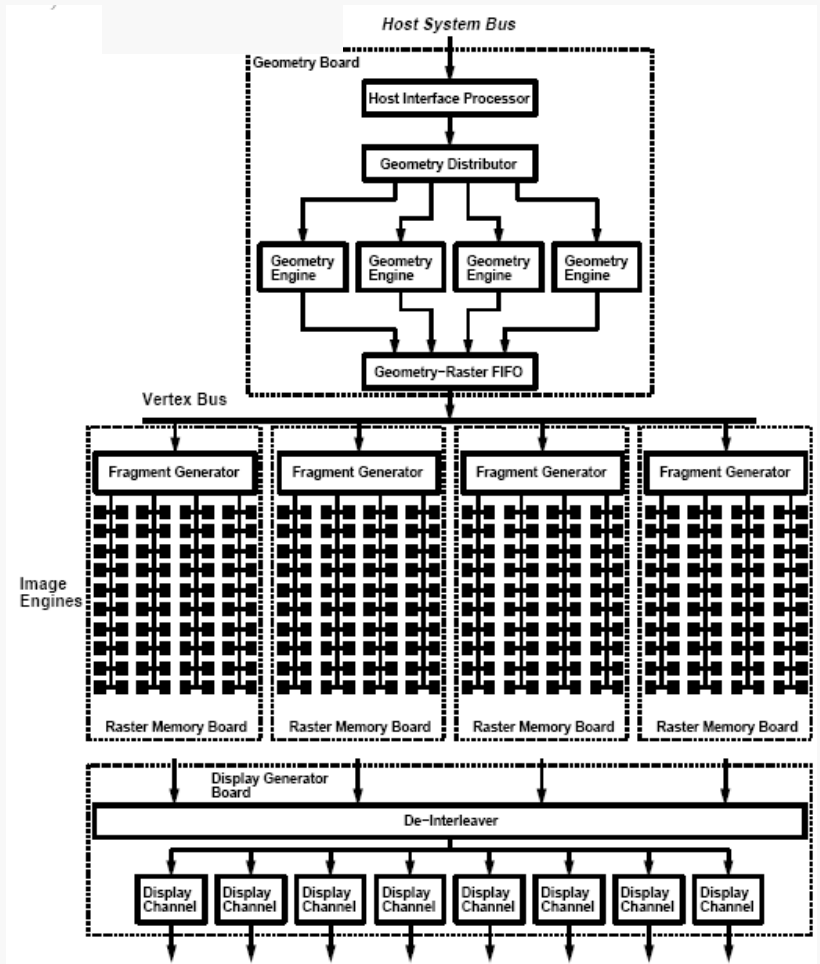
# Minimum Triangle Separation for Correct Z-Buffer Occlusion

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Microsoft Research Asia  
3 September 2006

# InfiniteReality

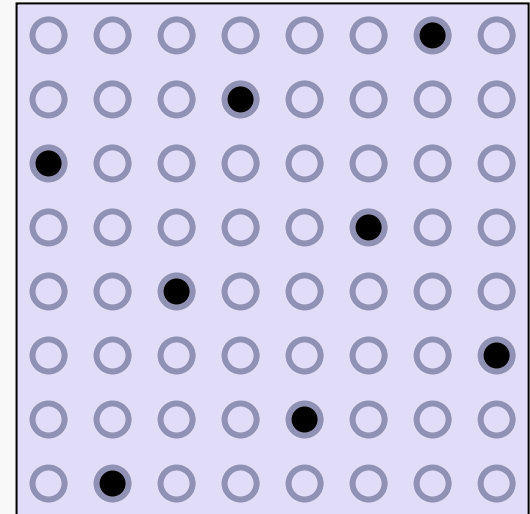


Figures taken from *InfiniteReality: A Real-Time Graphics System*, Proceedings of SIGGRAPH 1997



# Multisample Antialiasing

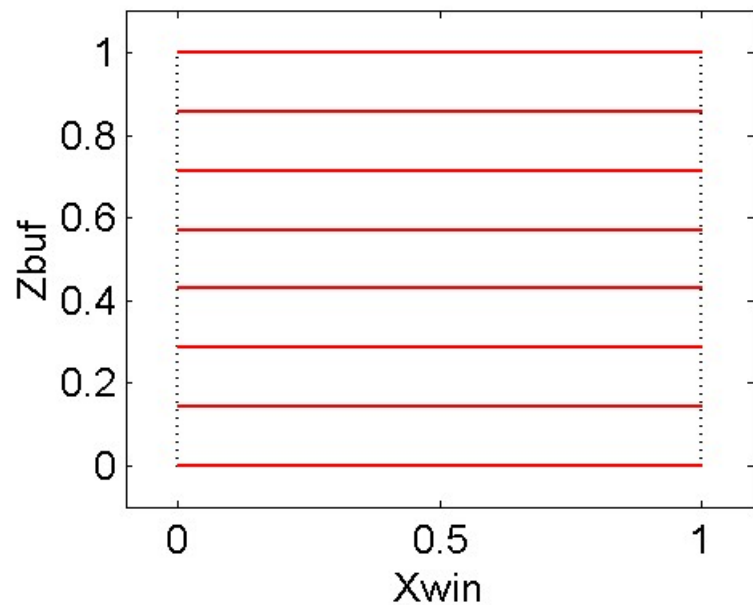
- Visual simulation requires high-quality and reliable antialiasing
- Eight samples per pixel
- Colors constant within fragments
  - Common cases compress well
  - Bandwidth reduction possible
- Z values vary within fragments
  - Required for interpenetration AA
  - Spatial compression is difficult
  - Bandwidth is excessive



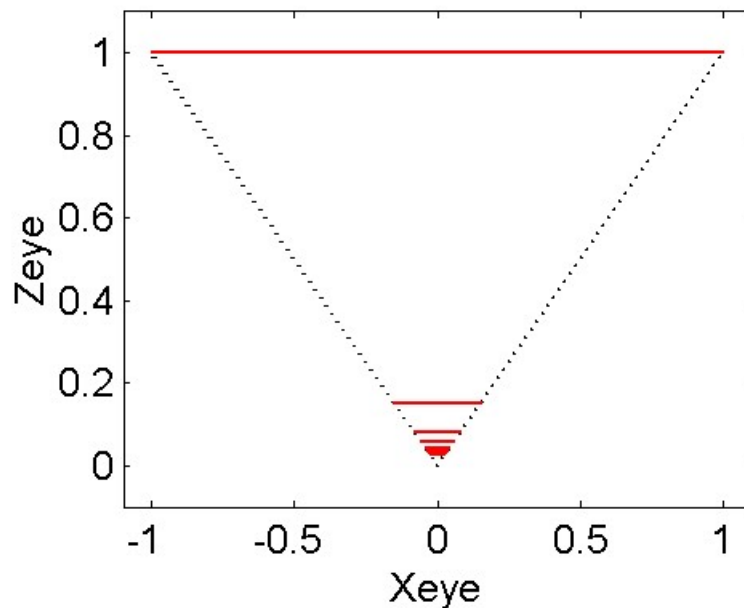
```
Struct sample {  
    int_12 red;  
    int_12 green;  
    int_12 blue;  
    int_24 z;  
};
```

Can a 16-bit z value be used?

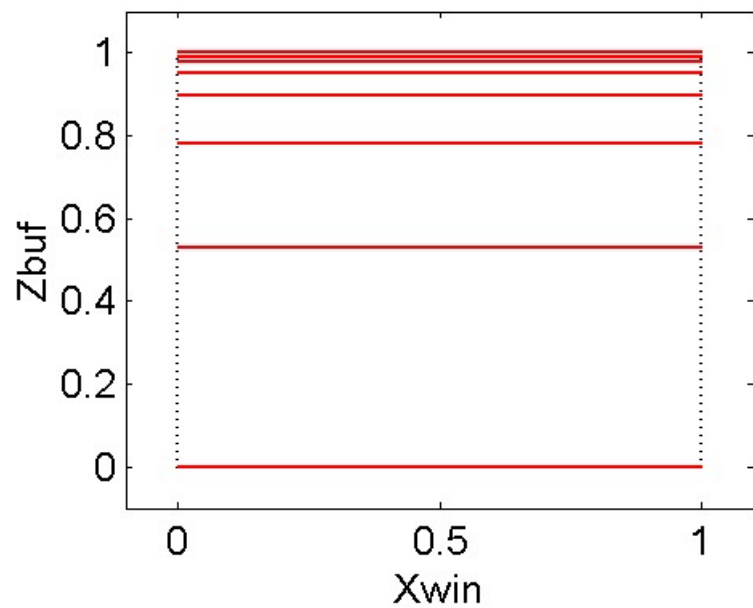
Integer Zbuf



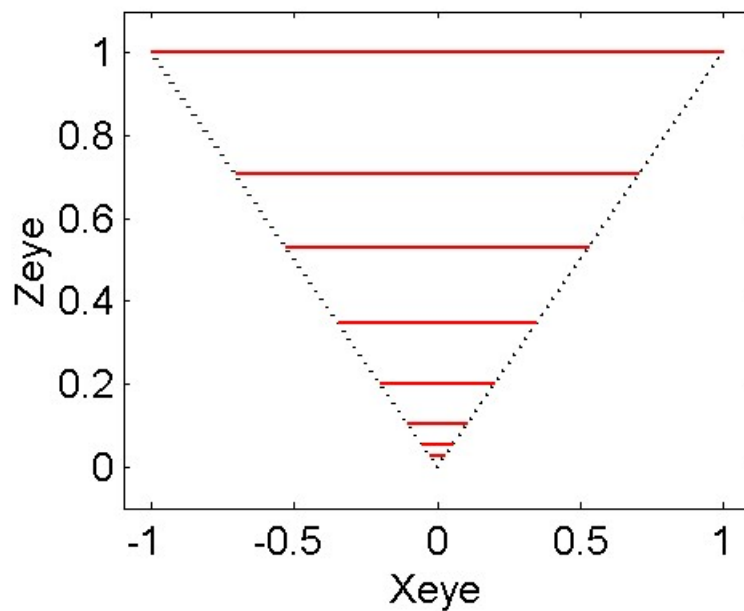
Reverse Mapped Integer Zbuf



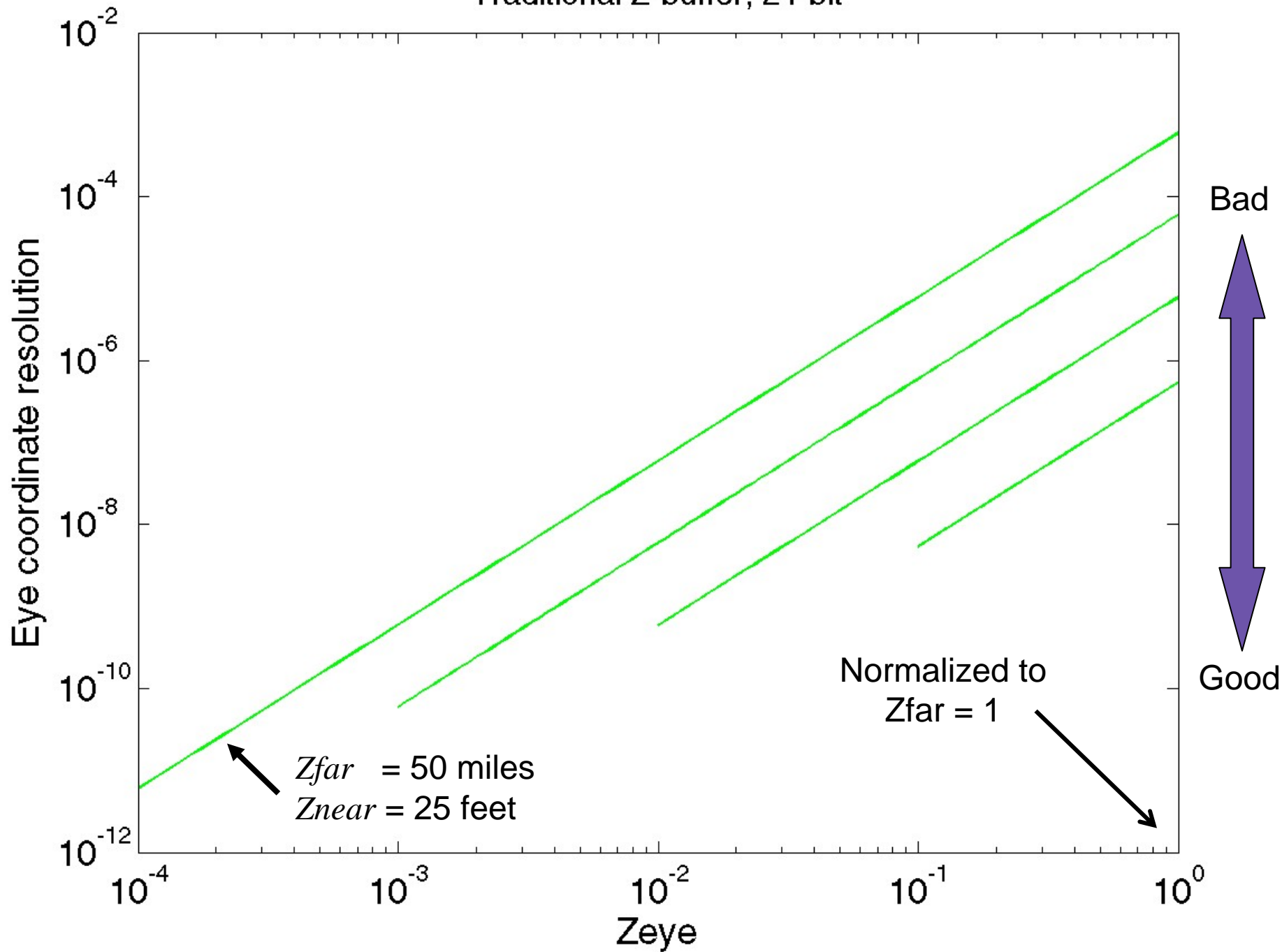
Warped Zbuf



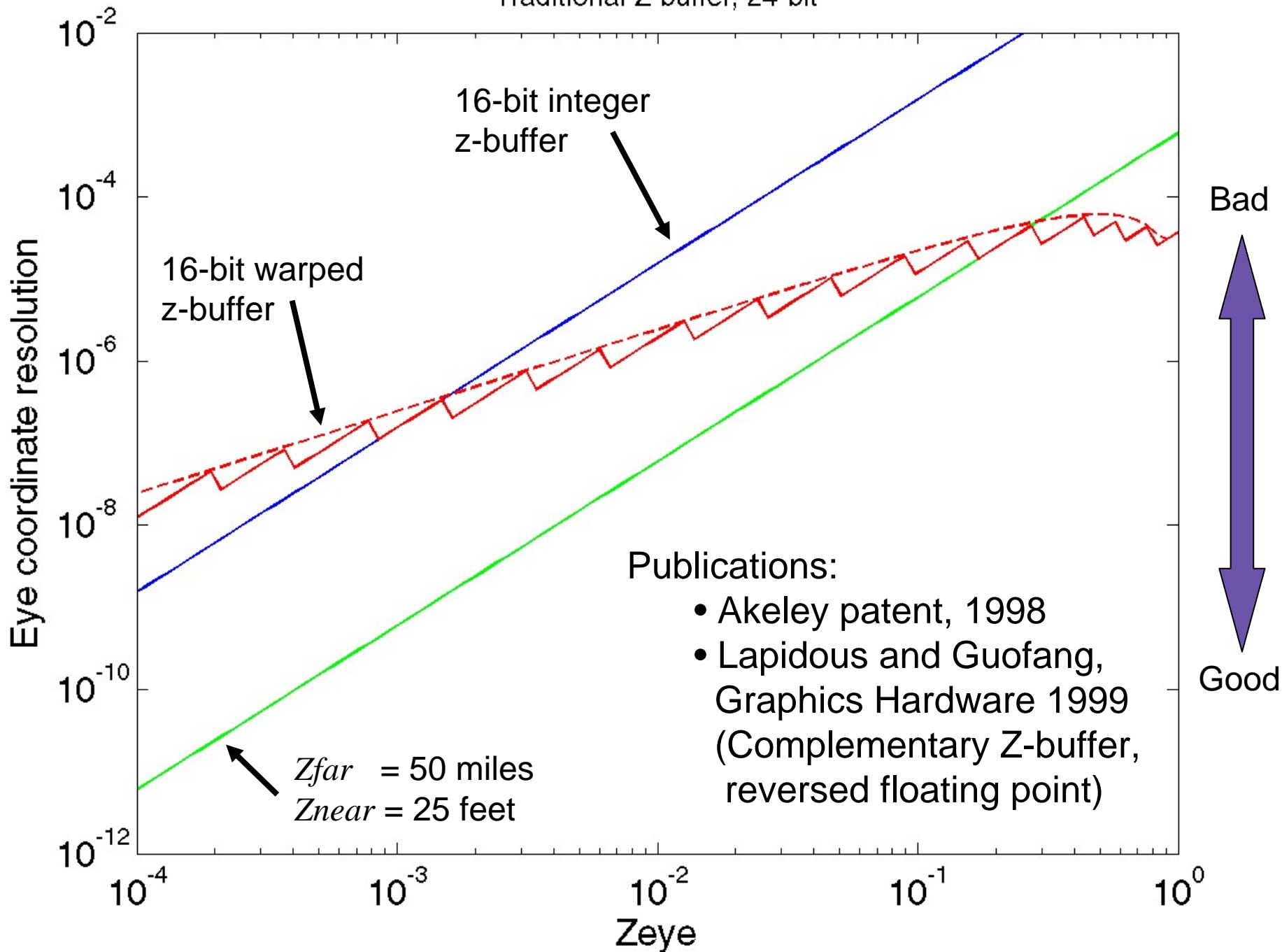
Reverse Mapped Warped Zbuf



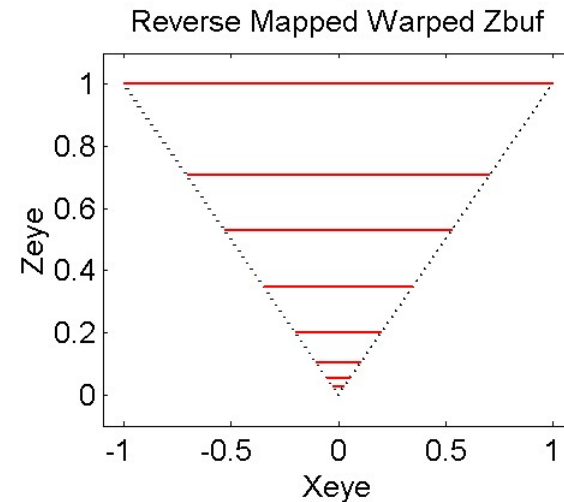
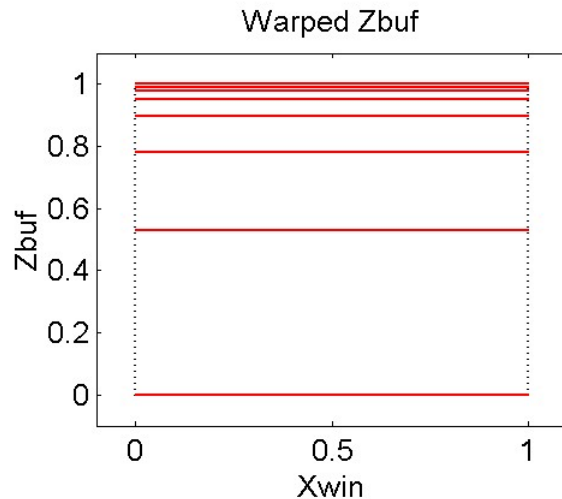
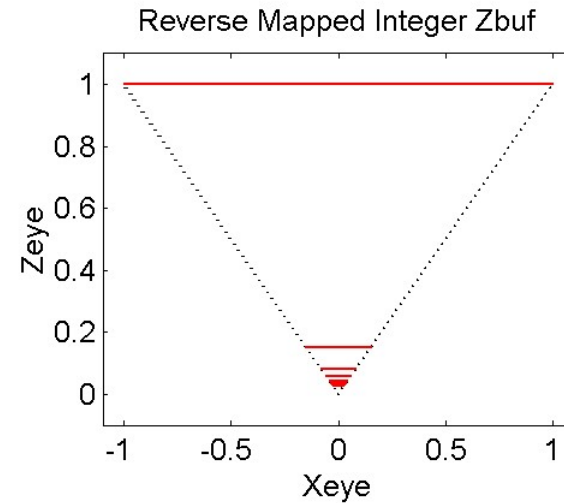
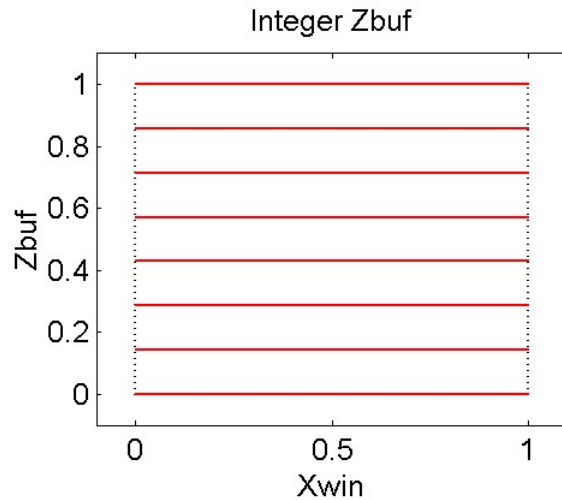
Traditional Z-buffer, 24-bit



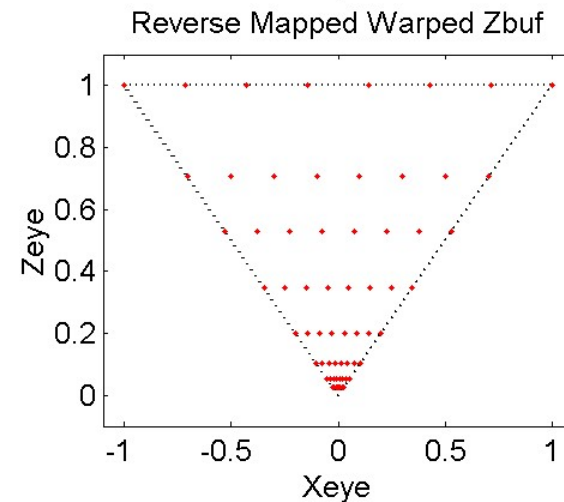
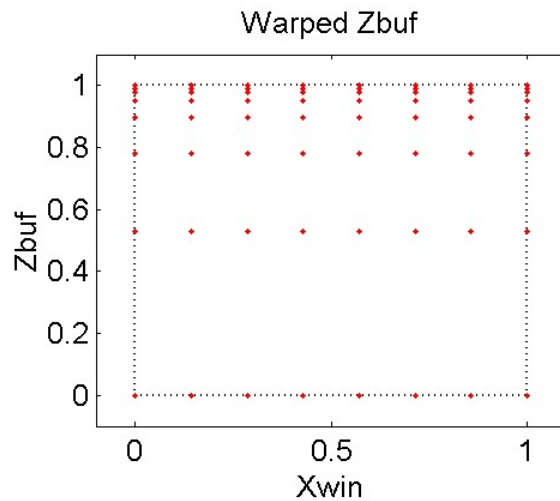
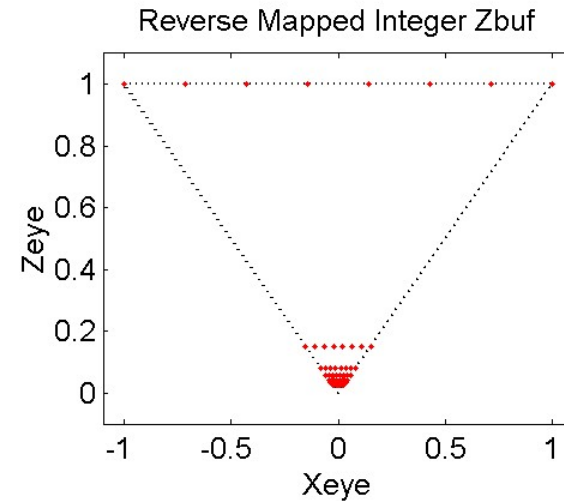
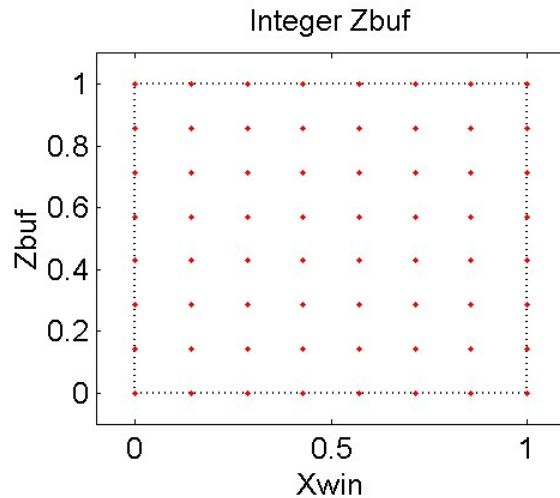
# Traditional Z-buffer, 24-bit



# Ignores $X_{win}$ and $Y_{win}$ Representation



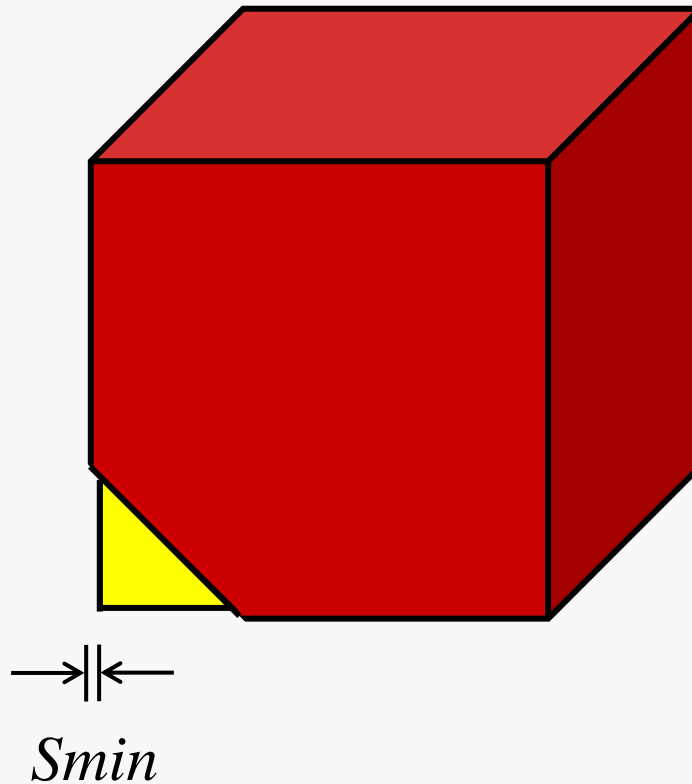
# Discrete $X_{win}$ and $Y_{win}$ affect $Z_{buf}$ values





# Minimum Separation

(Z-buffer resolution is like vacuum cleaner horsepower)



# Outline of Talk

- List assumptions and definitions
- Compute  $S_{min}$ 
  - Treating  $X_{win}$ ,  $Y_{win}$ , and  $Z_{buf}$  as discrete representations
  - Treating all other arithmetic as ideal
- Compute  $S_{min}$  again
  - Accumulating error due to all discrete representations from eye-coordinates to the z-buffer
    - Ignoring clipping
    - Assuming high-quality rasterization
- Suggest guidance opportunities
- Conclude

**We verify all analysis with simulation results**



# Assumptions and Definitions

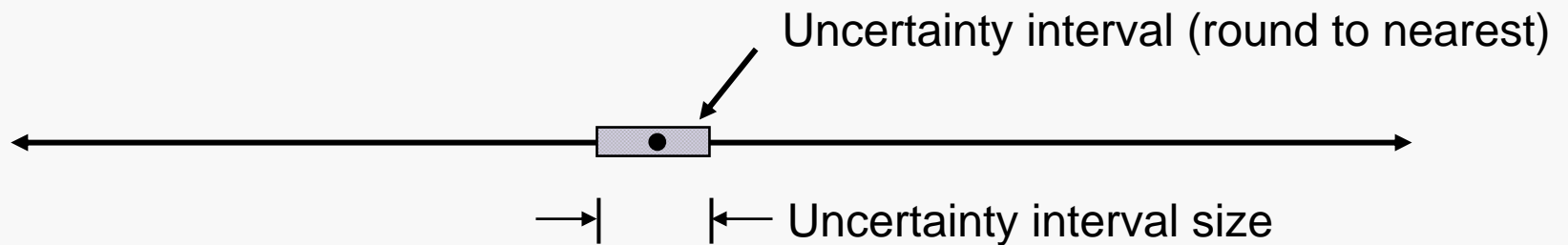
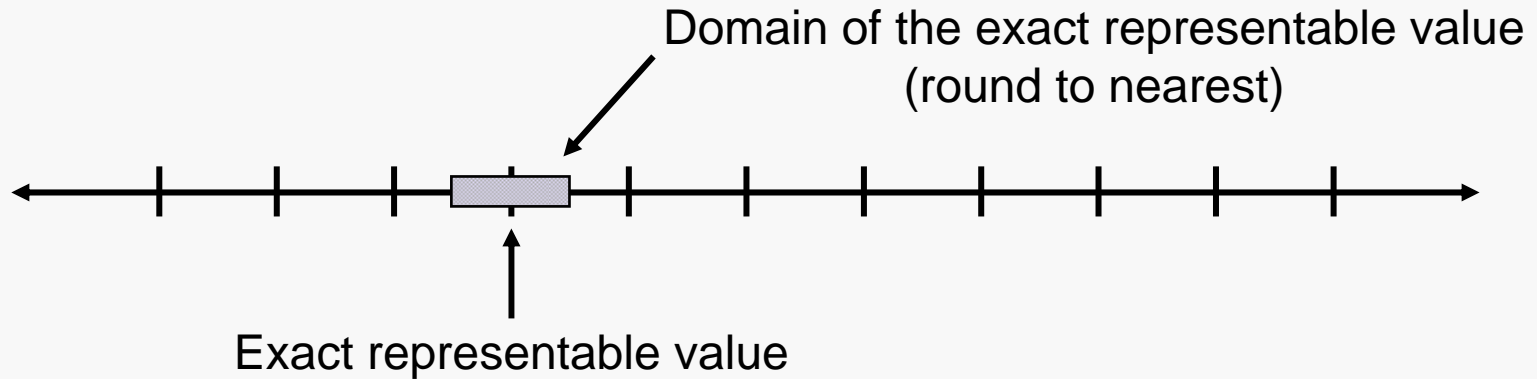


# Assumptions

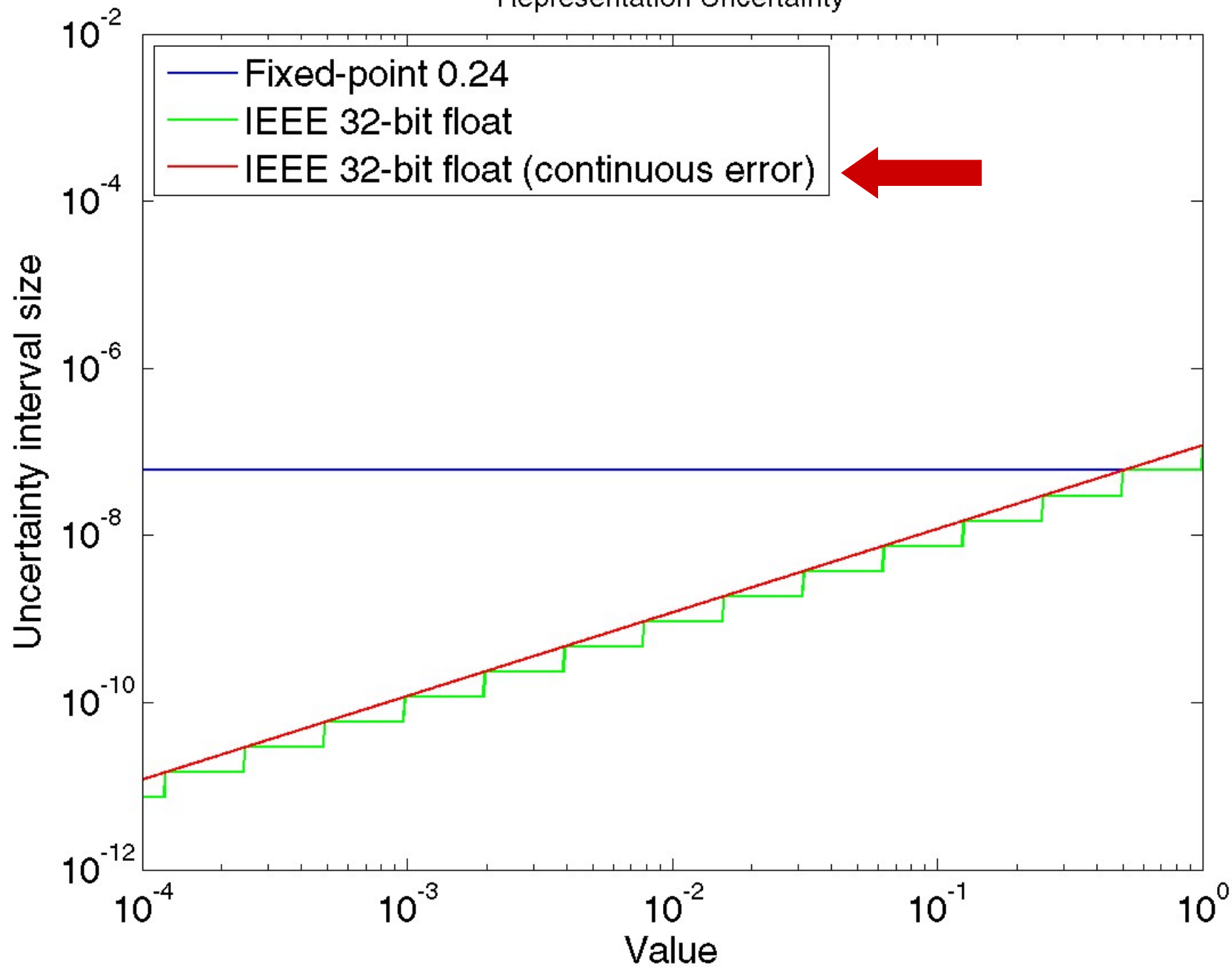
- Standard OpenGL/Direct3D-like pipeline
  - Used in standard way (e.g., not ray tracing)
- Triangles only
  - No points
  - No lines



# Uncertainty Intervals



Representation Uncertainty



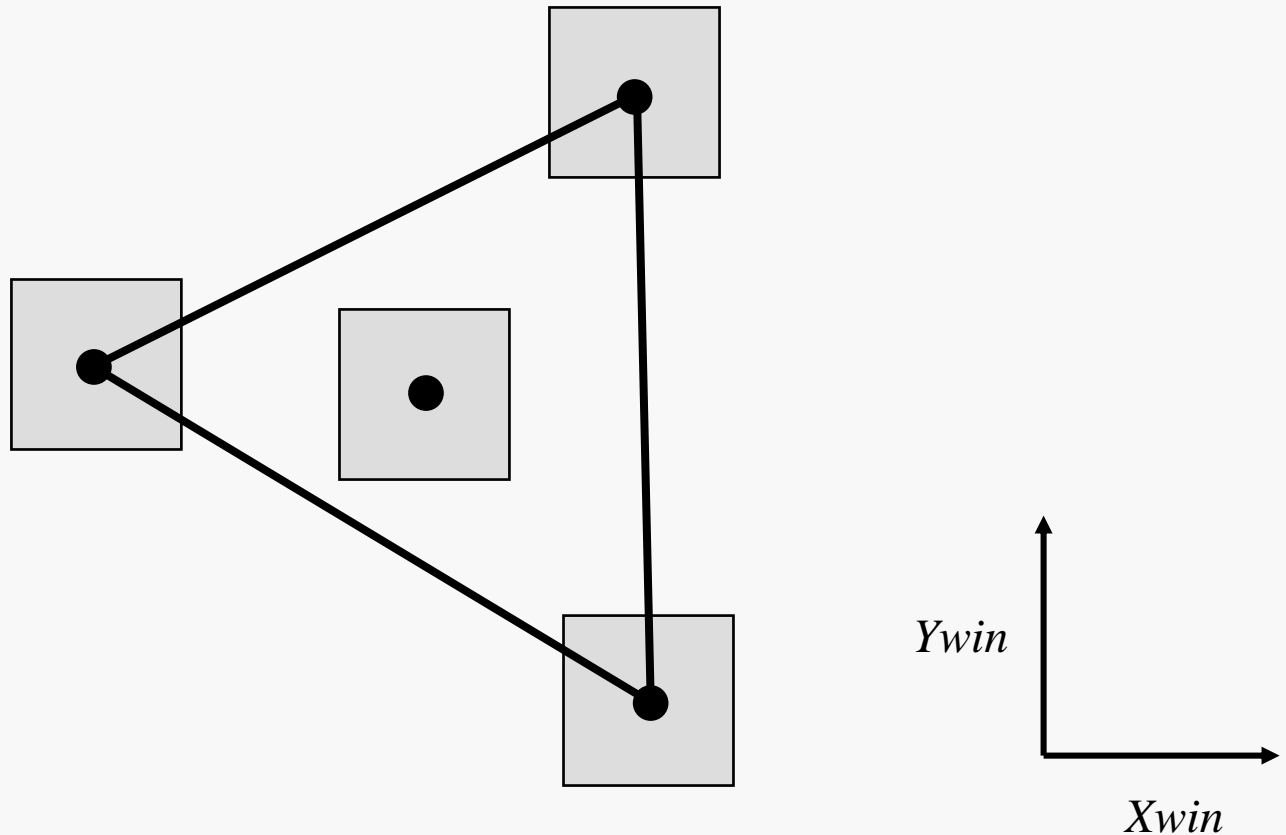
# Compute $S_{min}$

(with discrete  $X_{win}$ ,  $Y_{win}$ , and  $Z_{buf}$ )



# *Xwin, Ywin* Uncertainty Square

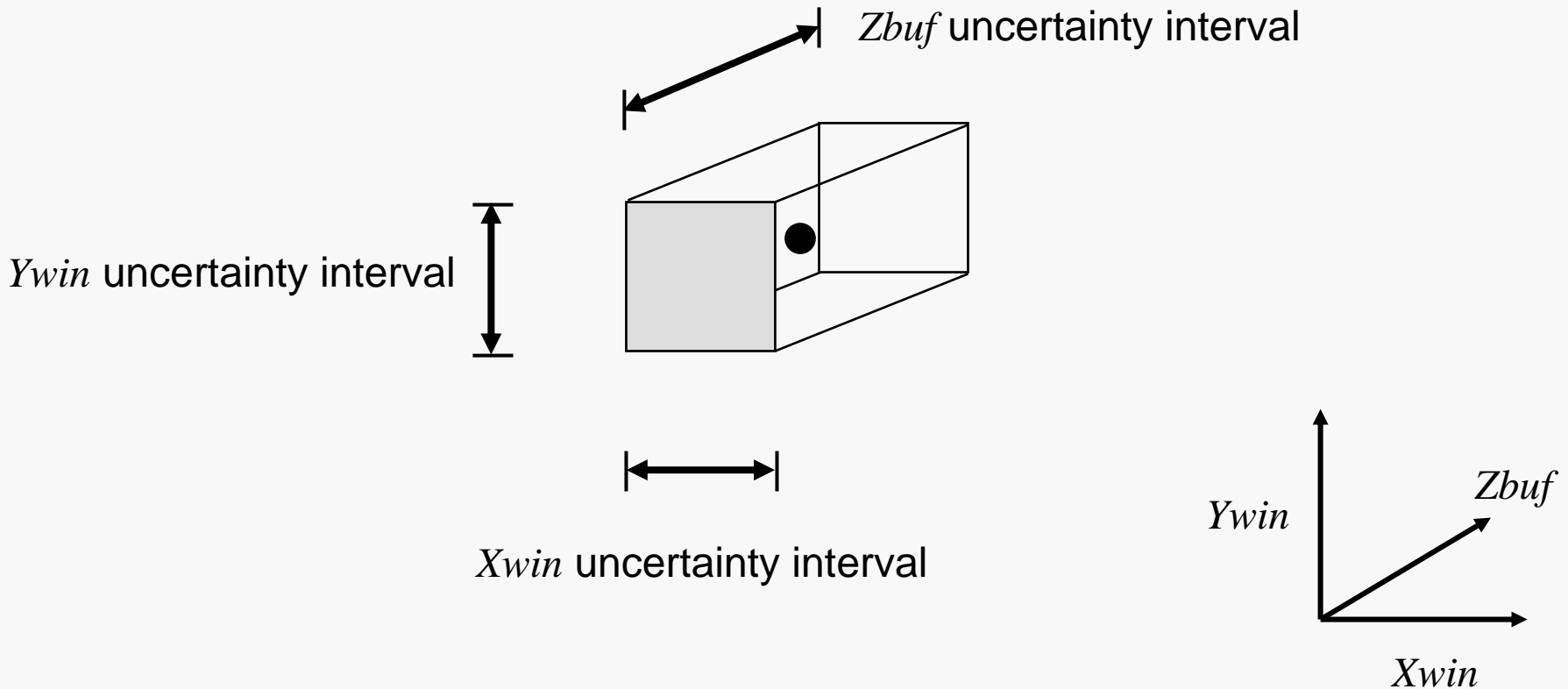
For any  $x, y$  location in the window-coordinate triangle





# Uncertainty Cuboid

For any point on the surface of the 3-D triangle

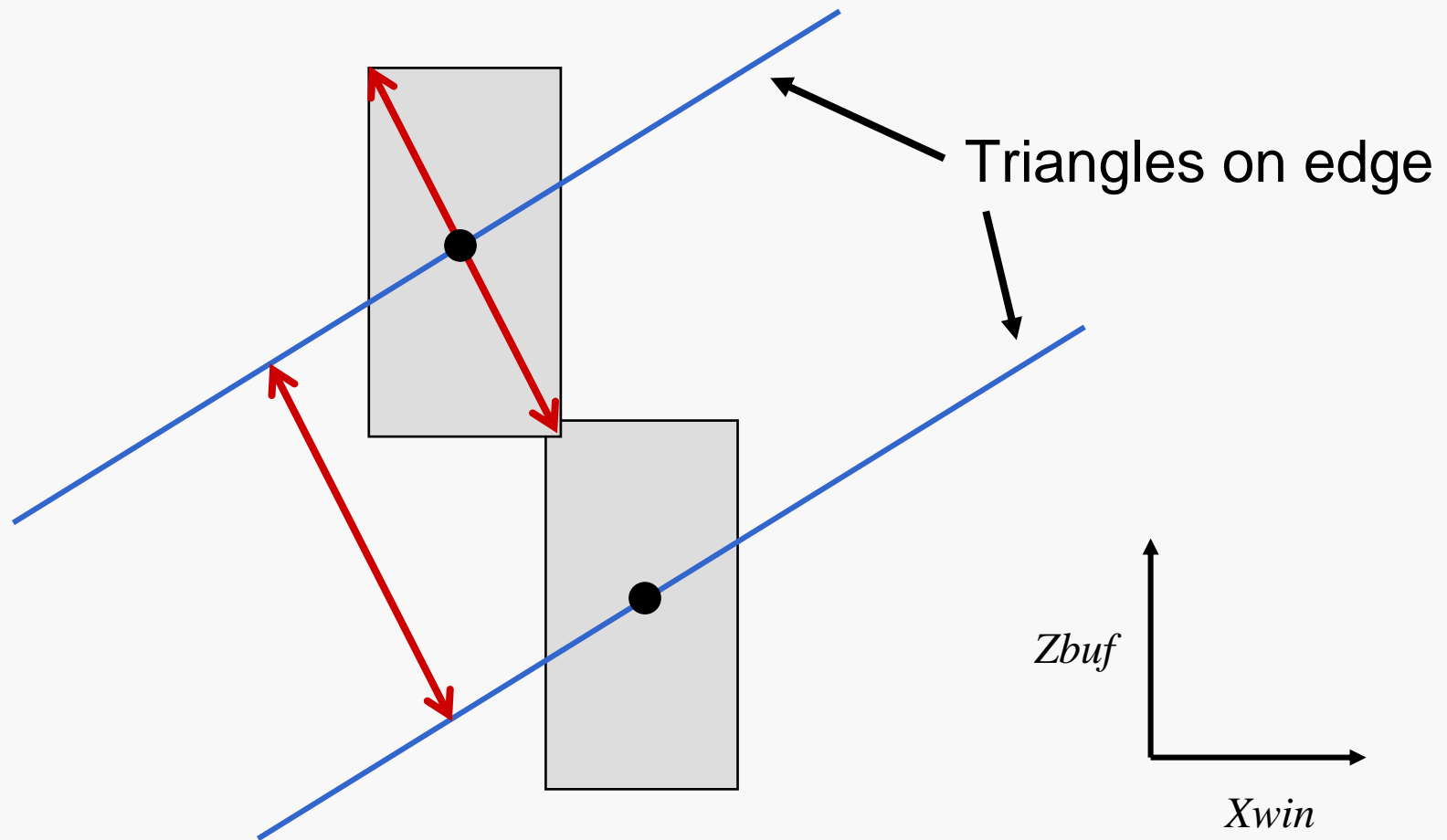


# What is $S_{min}$ ?

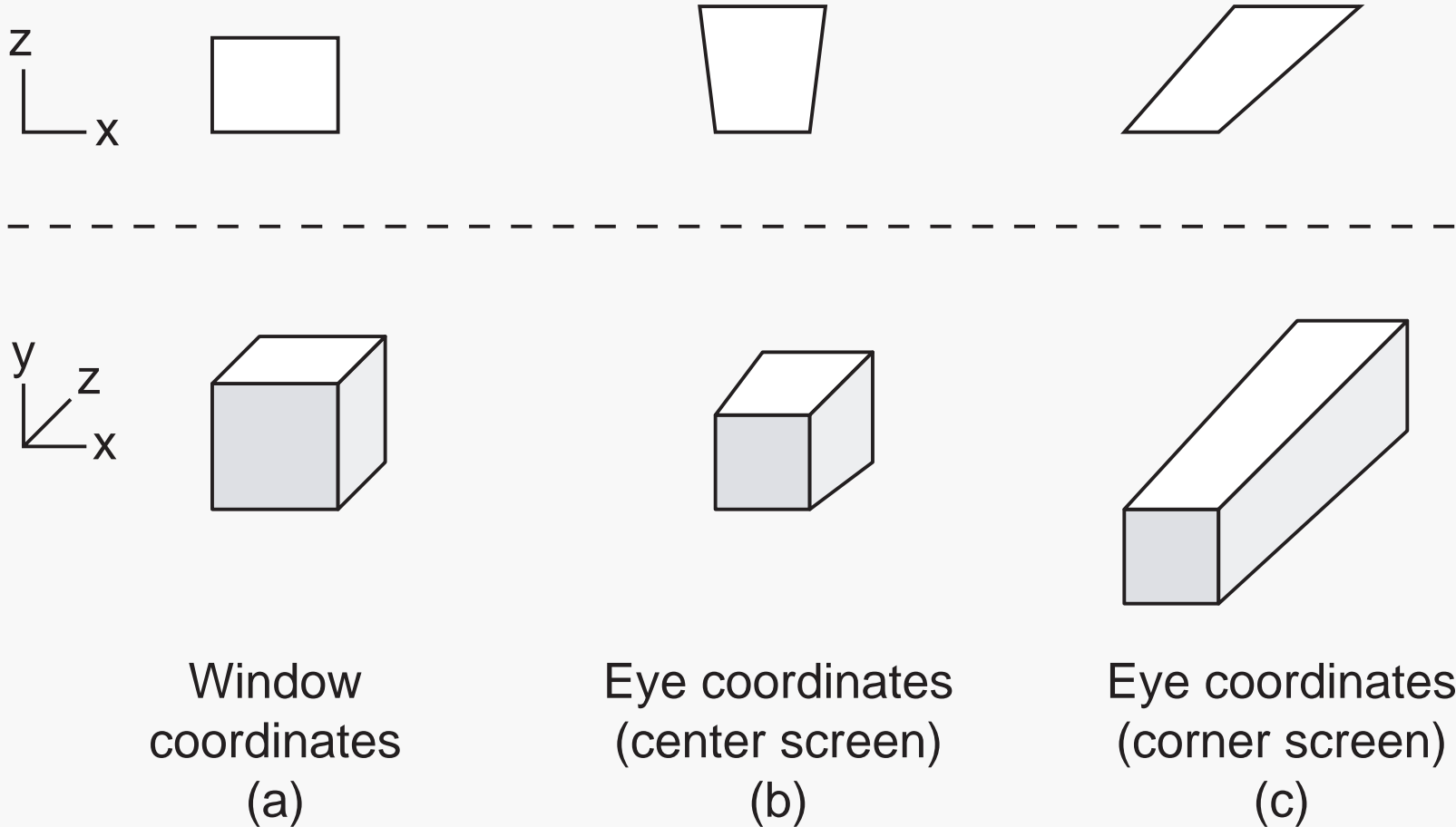
- Considering only  $Z_{buf}$ 
  - Depth of the uncertainty cuboid
- Considering only  $X_{win}$  and  $Y_{win}$ 
  - Length of diagonal of the uncertainty square
- Considering  $X_{win}$ ,  $Y_{win}$ , and  $Z_{buf}$ 
  - Length of diagonal of the uncertainty cuboid

Worst case is for triangles that are perpendicular to the diagonal

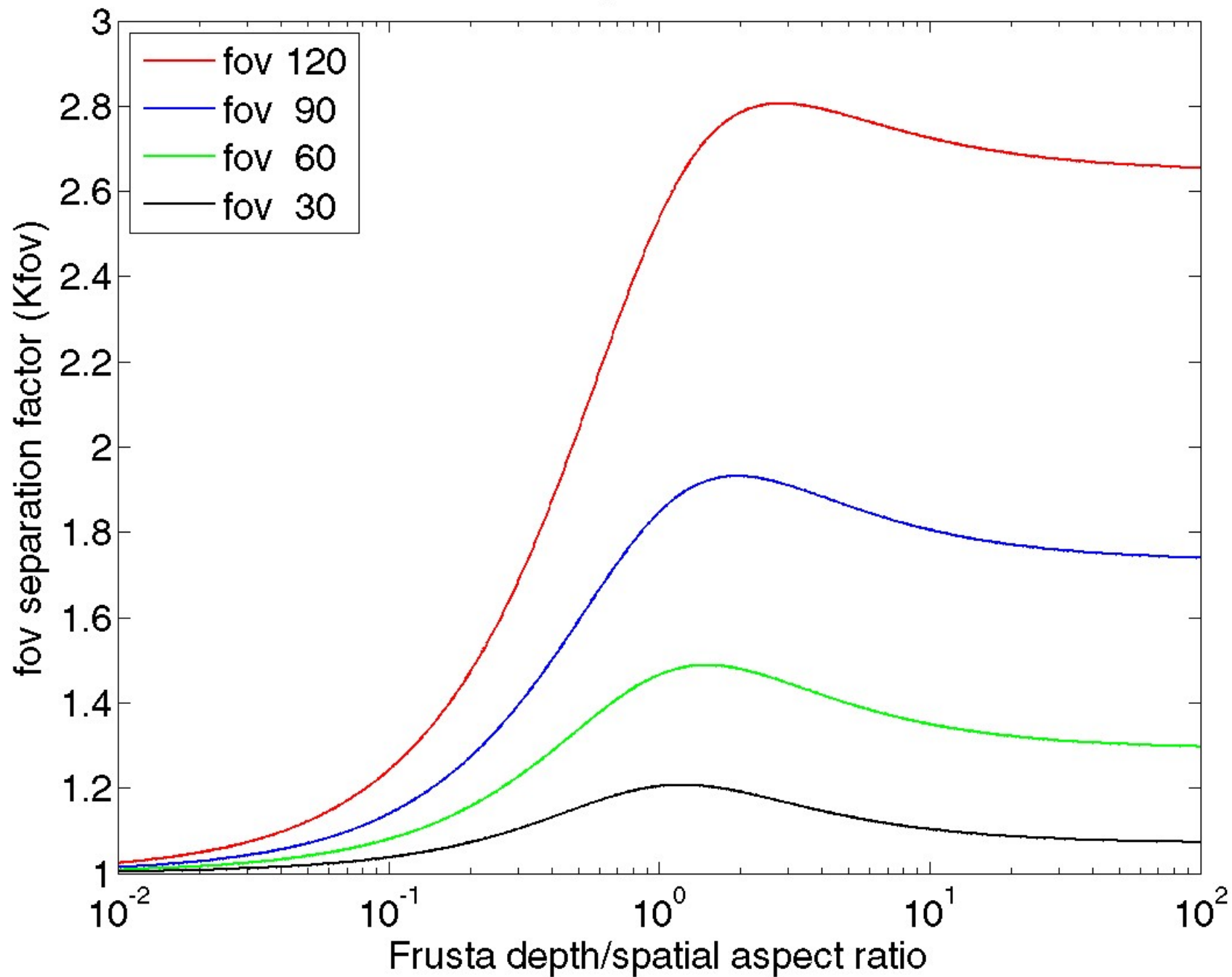
# Uncertainty Volume Overlap $\rightarrow$ Failure



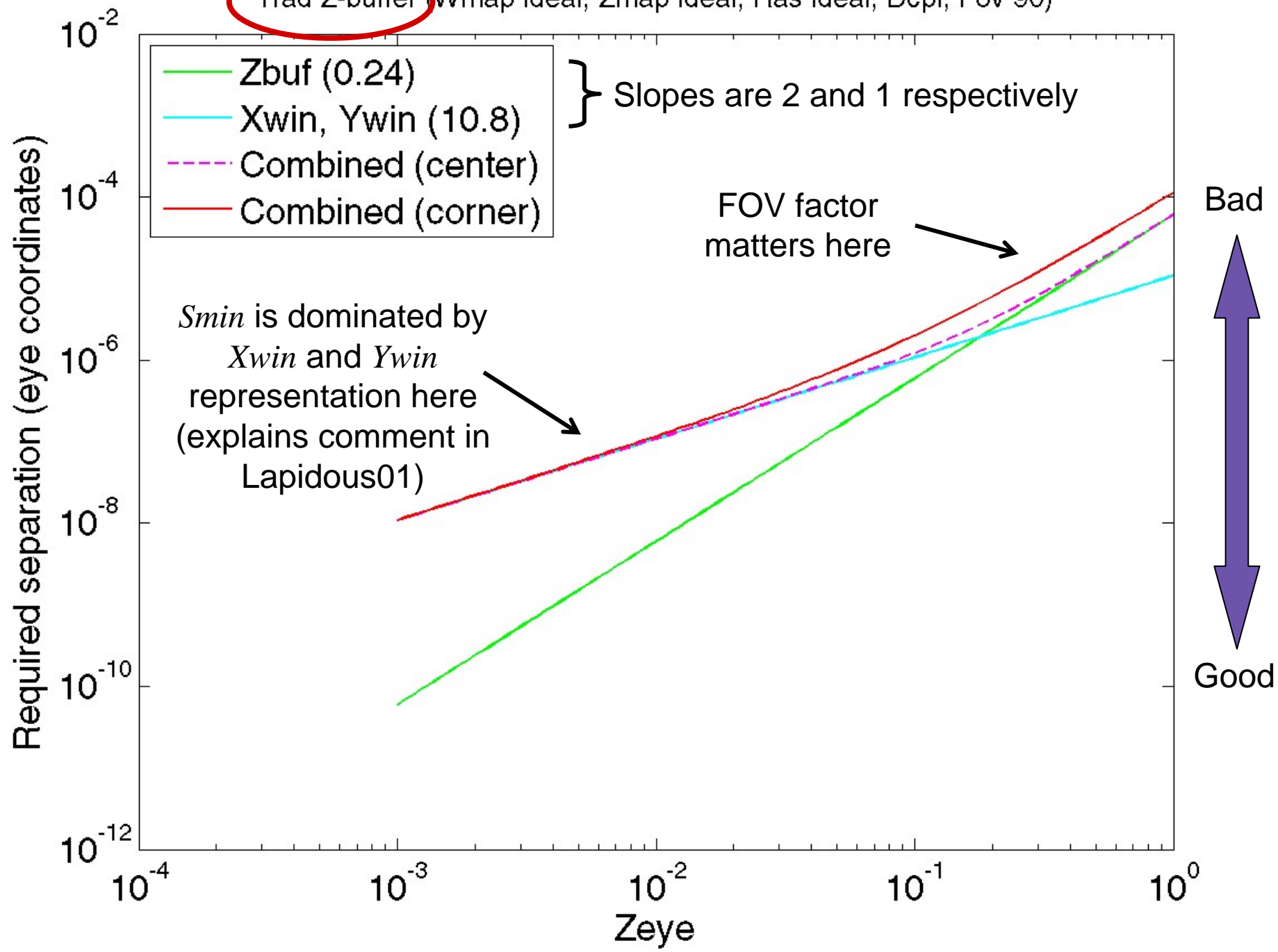
# Wide Field of View Increases $S_{min}$



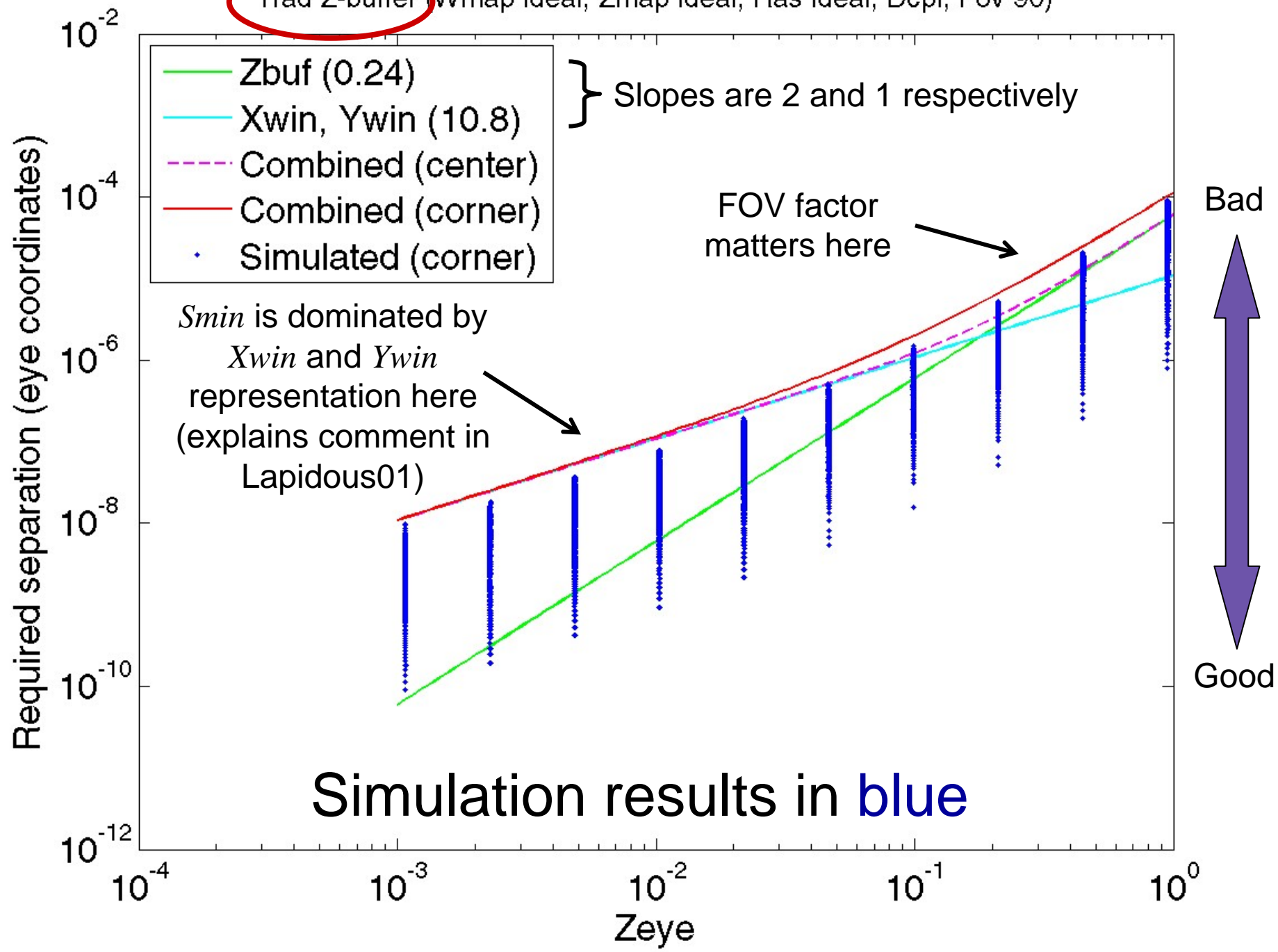
fov separation factor



Trad Z-buffer (Wmap ideal, Zmap ideal, Ras ideal, Dcpl, Fov 90)



Trad Z-buffer (Wmap ideal, Zmap ideal, Ras ideal, Dcpl, Fov 90)



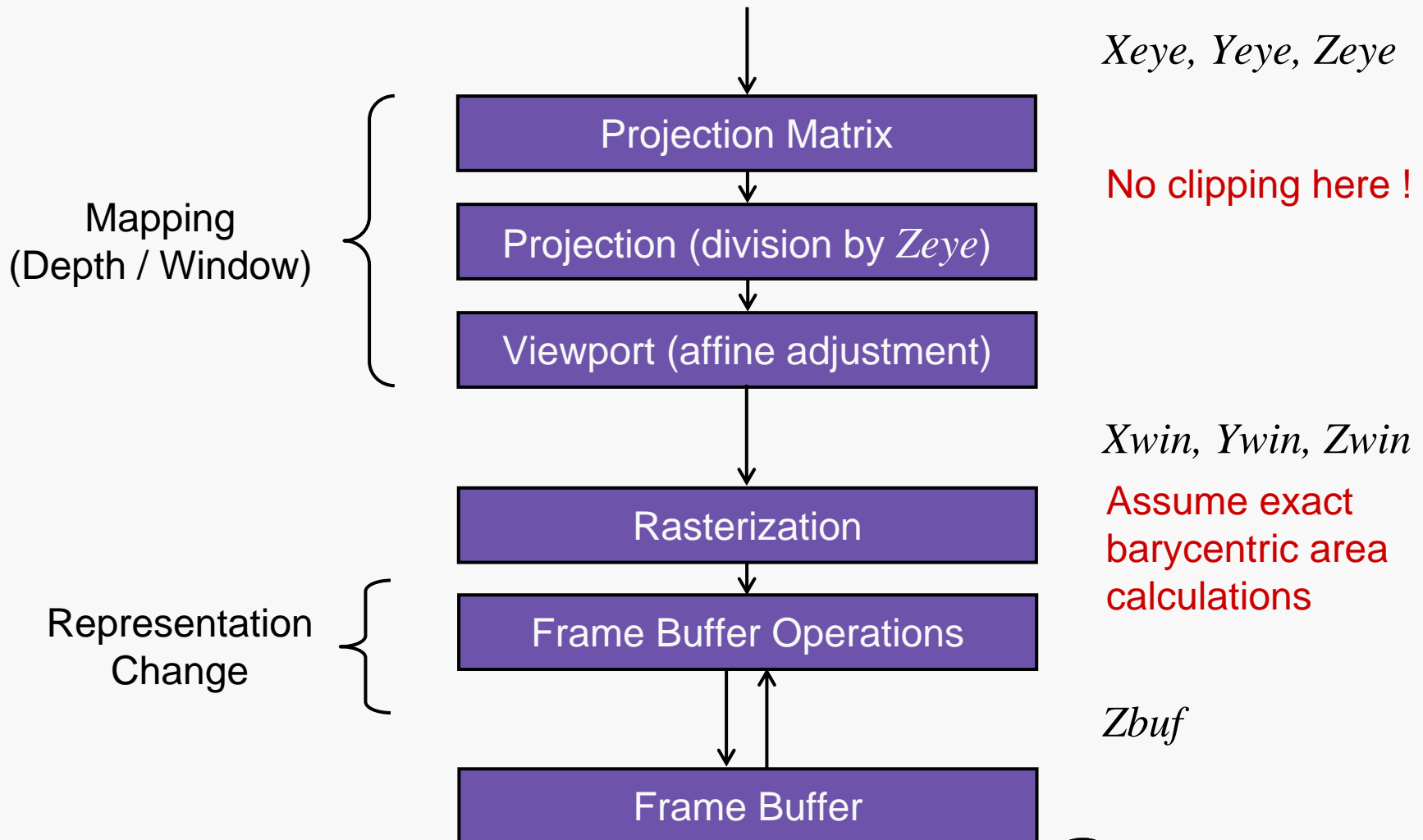
# Compute *Smin* again

(all values treated as discrete)





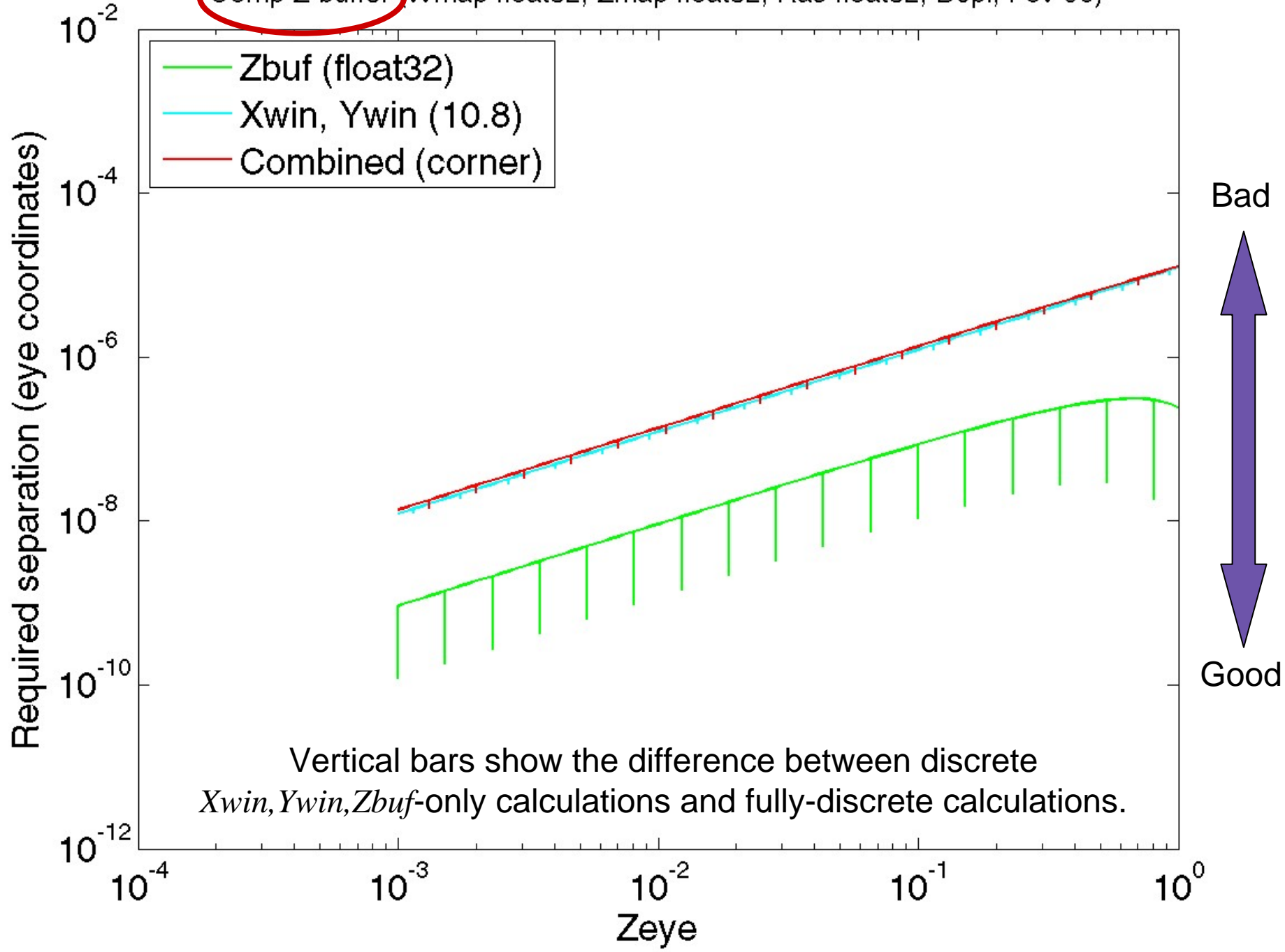
# Cumulative Uncertainty Arithmetic



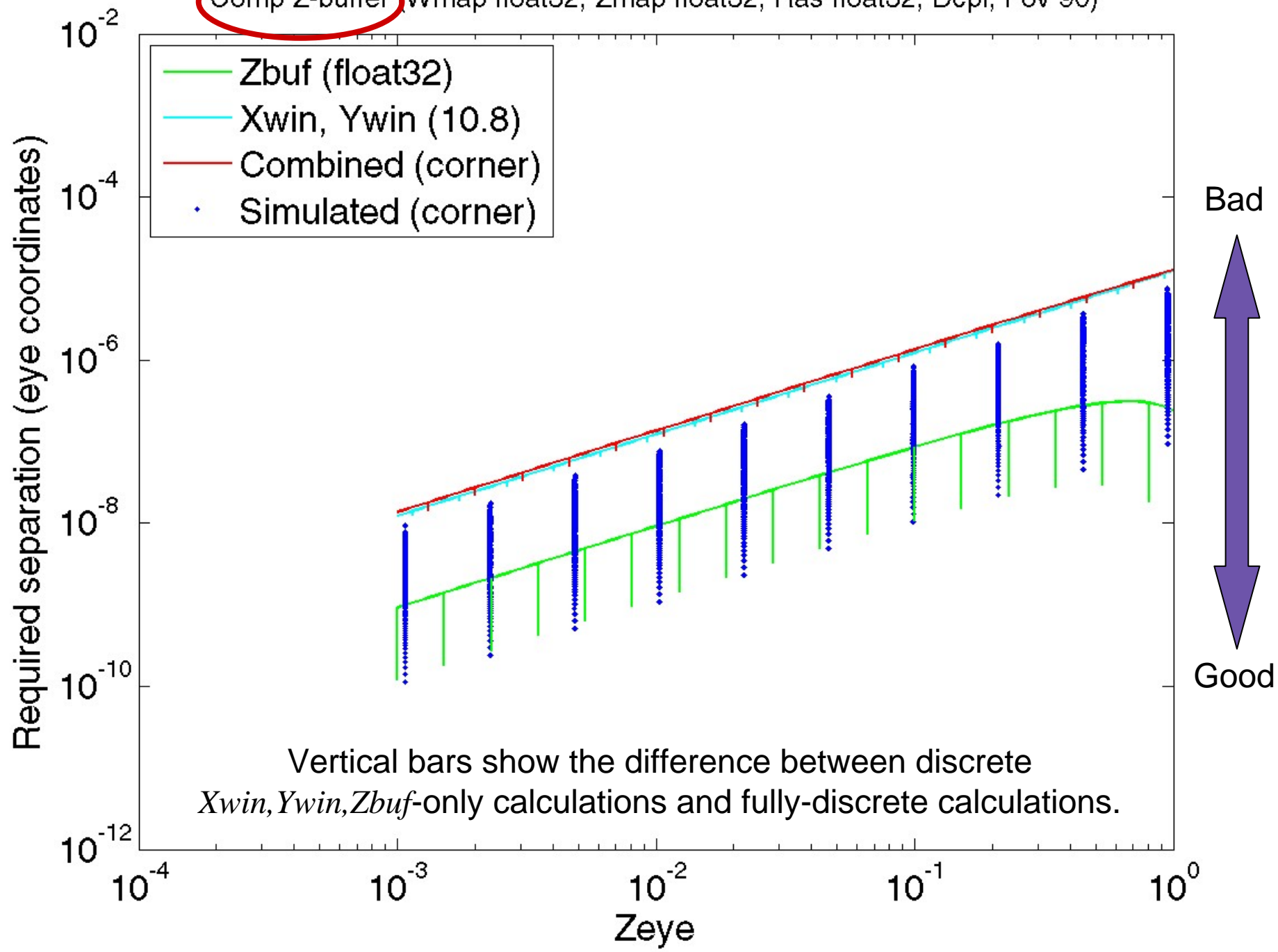
# Interval Analysis

- We wrote our own interval analysis tool
- API allows specification of
  - Equation
  - Representations of operands and intermediates
  - Values of operands
- Evaluation is done using “ideal” arithmetic
  - Current ideal is IEEE 64-bit
- Handles polynomials correctly, e.g.  $Z_{win} = \frac{C \cdot Z_{eye} + D}{Z_{eye}}$
- Reverse map to eye coordinates

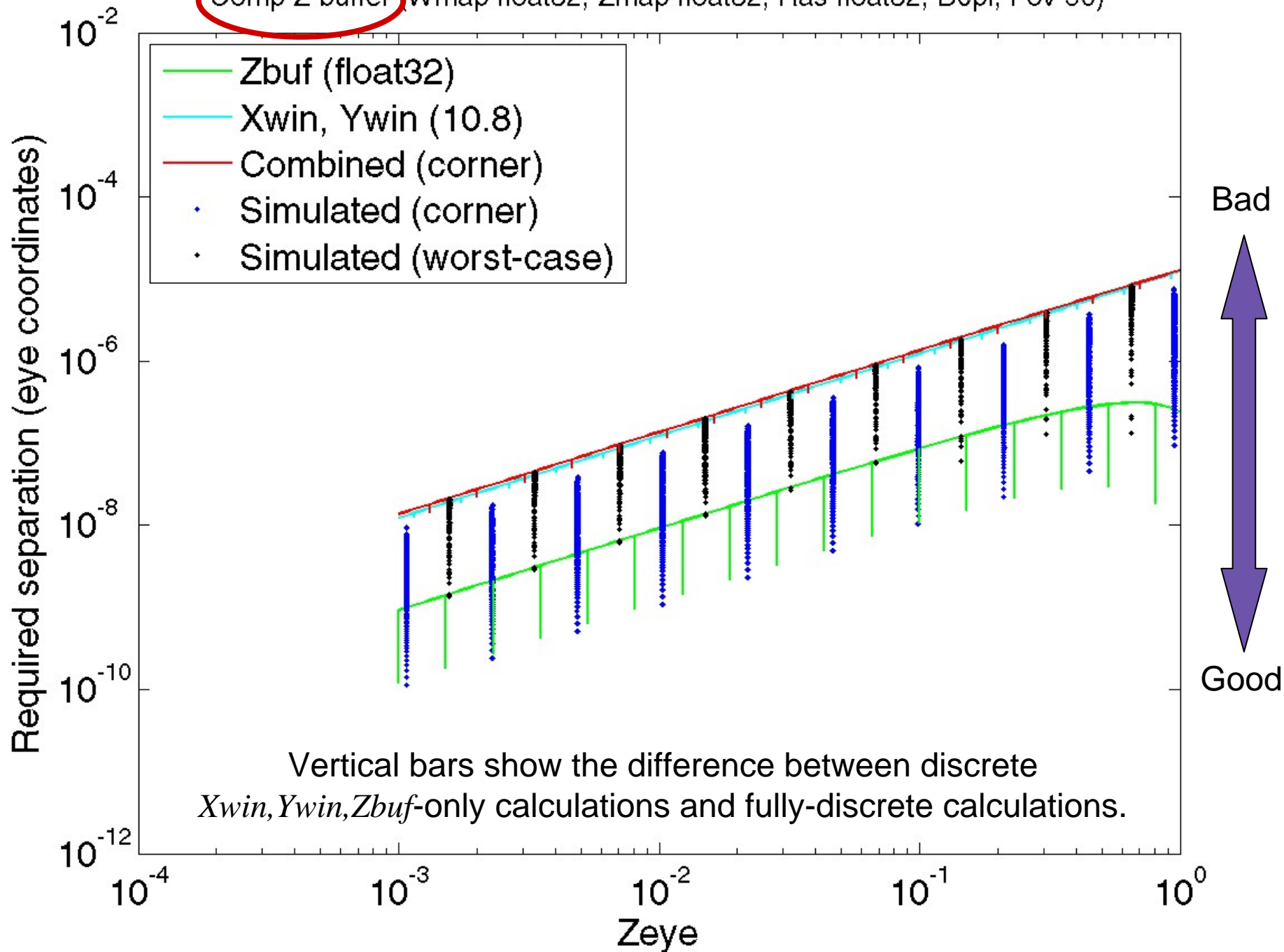
Comp Z-buffer (Wmap float32, Zmap float32, Ras float32, Dcpl, Fov 90)



Comp Z-buffer (Wmap float32, Zmap float32, Ras float32, Dcpl, Fov 90)



Comp Z-buffer (Wmap float32, Zmap float32, Ras float32, Dcpl, Fov 90)

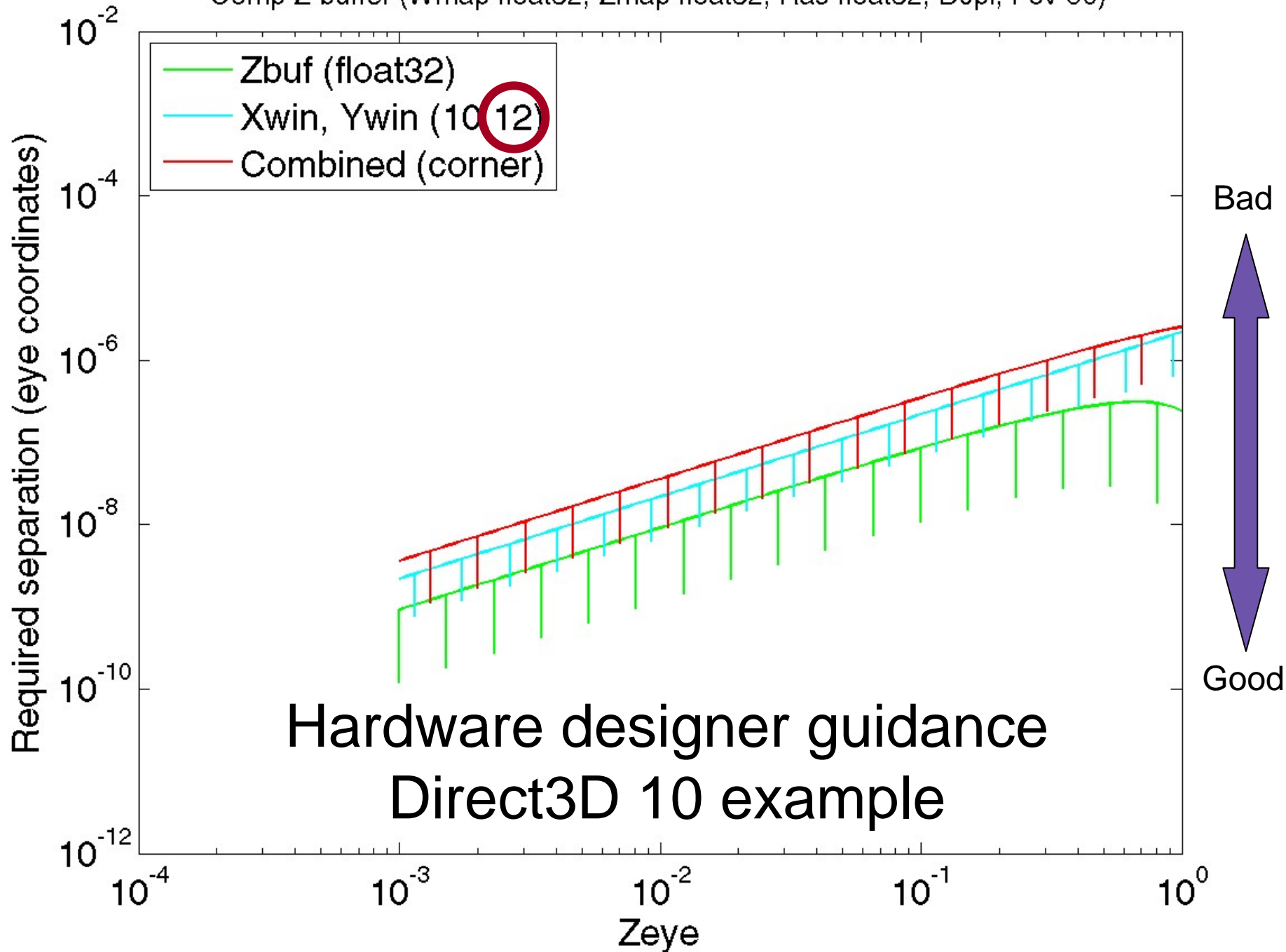


# Guidance

(for hardware designers  
and application developers)



Comp Z-buffer (Wmap float32, Zmap float32, Ras float32, Dcpl, Fov 90)



# Application Developer Guidance

- Can specify a tight  $S_{min}$  bound for a specific GPU !
- Linear increase of  $S_{min}$  with  $Z_{eye}$ 
  - Assume (near linear) complementary z-buffer
  - Matches linear  $X_{win}$ ,  $Y_{win}$  behavior
  - Is consistent with geometric LOD

$$S_{min} = K_{sep} Z_{eye}$$



Field of View

	30	60	90
512			
1024			
2048			

Viewport Size





# Conclusion

- Uncertainty analysis gives nice understanding of  $S_{min}$ 
  - Window-coordinate representation matters
  - Wide FOV can increase  $S_{min}$  by 2x to 3x
- With this understanding, we can give guidance to
  - Hardware designers
  - Application developers (with community agreement)
- In the future, we could
  - Analyze contribution of clipping arithmetic
  - Better understand worst-case interval evaluation
  - Extend to new areas (e.g., shadow generation)



# Thanks to

- Jonathan Su, my intern at MSR Asia
- David Blythe and Amar Patel of the DX10 team
- Marcel Gavriľiu and Jim Kajija, for help with interval analysis
- Turner Whitted and Harry Shum, for allowing me to do this research
- The Eurographics Hardware Workshop, now Graphics Hardware, for inviting me to speak in 1991

