A Flexible Simulation Framework for Graphics Architectures



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Motivation

- No GPU simulators available in academia
 - Vendor simulators not available to academics
 - Probably lack necessary flexibility
- SimpleScalar has made a huge impact in the academic GP architecture community
 - Required a few years before work became interesting to industry
 - Started with incremental ideas that industry had already considered or been considering
 - Now 150-300 papers/year use SimpleScalar
 - 30%-50% are looked at by industry
 - At least 1%-2% of the ideas actually make it into products
- Hope to elicit the same kind of innovations in the GPU community



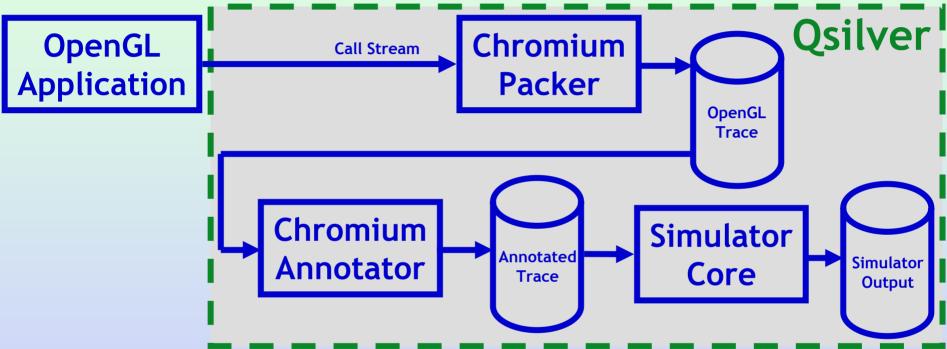
- An architectural simulator for GPUs
- Makes possible academic study of a wide array of architectural techniques
- Runtime configurable
- Traces any OpenGL application
- Small, extensible code-base



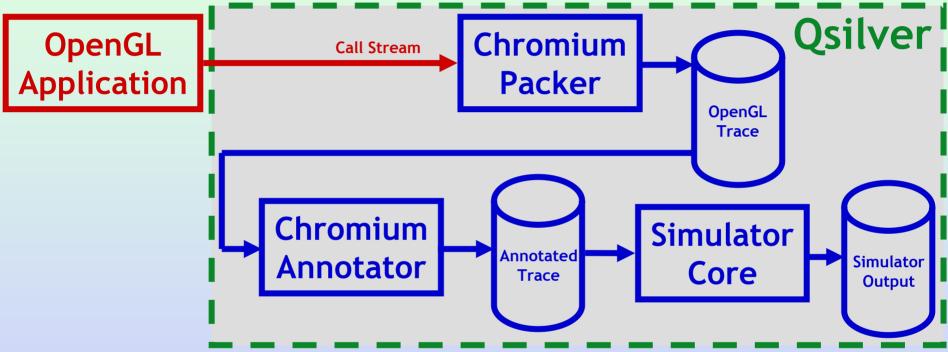


- OpenGL stream interceptor and transformer
- Allows easy manipulation of the OpenGL call stream
- Usually used for parallel rendering applications
- No need for source code of OpenGL application



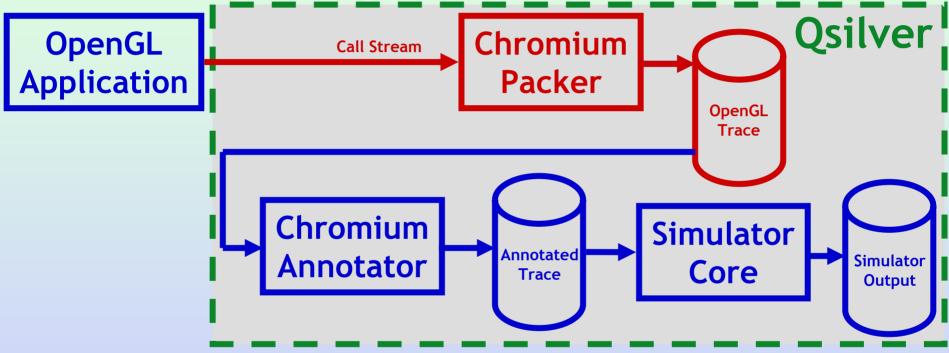






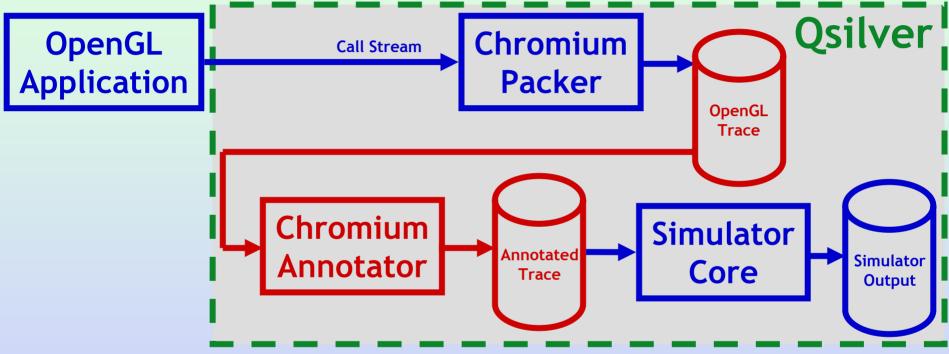
 An OpenGL application's call stream is intercepted by Chromium





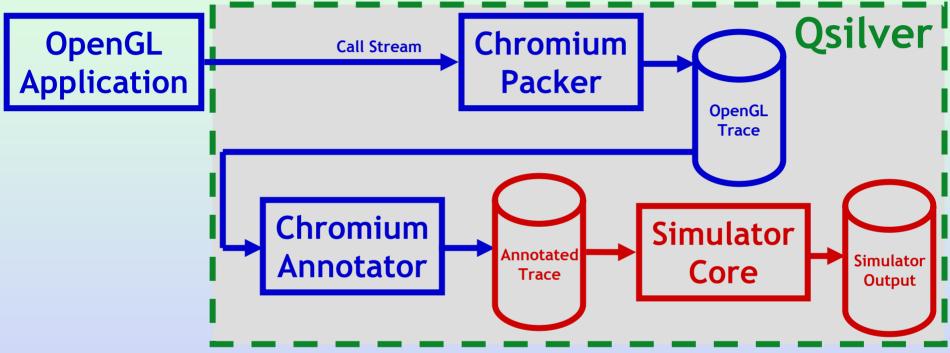
 The call stream is passed to the packer, which generates an OpenGL trace file





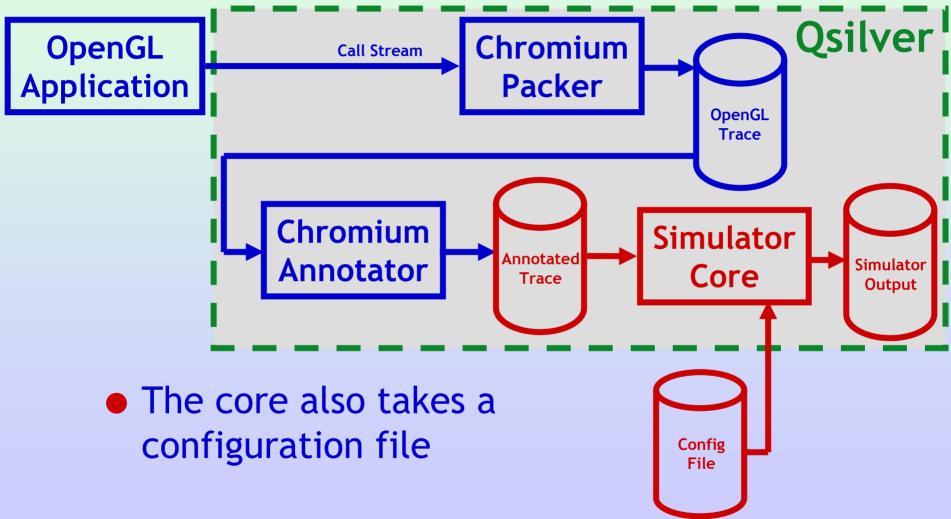
 The annotator reads the OpenGL trace and produces an annotated trace, which is the input to the simulator core



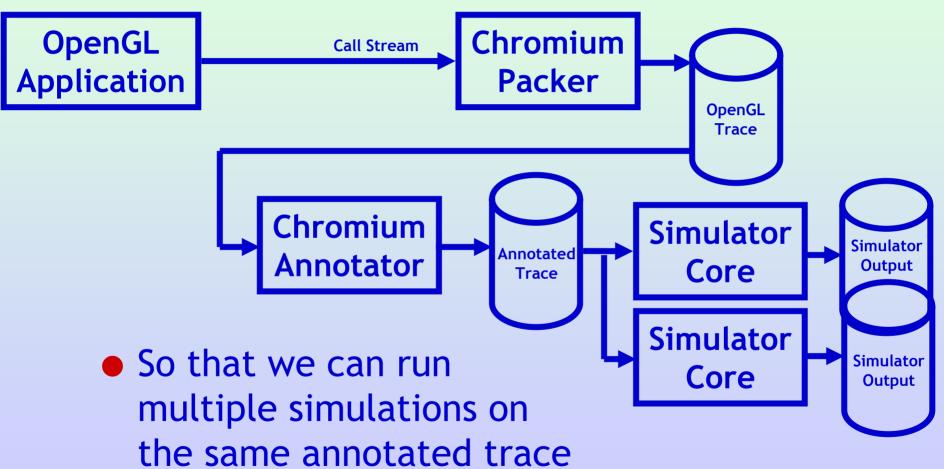


 The simulator core reads the annotated trace and produces the simulation results

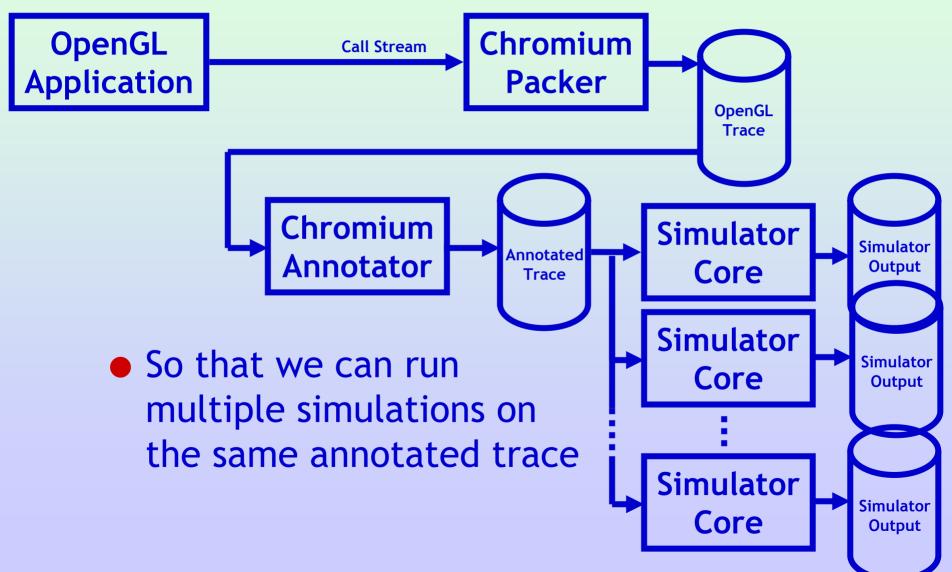












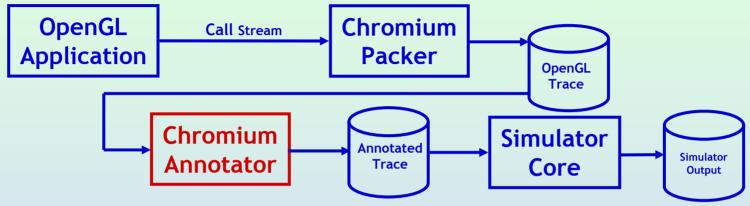


Example: Counting Fragments

- OpenGL stream is transformed so that all geometry is rendered triangle by triangle
- Occlusion query wrapped around every triangle
- Two passes for every triangle
 - First: With depth buffer and depth test disabled
 - Counts all fragments generated
 - Second: With depth buffer and depth test enabled
 - Counts only fragments which pass depth test



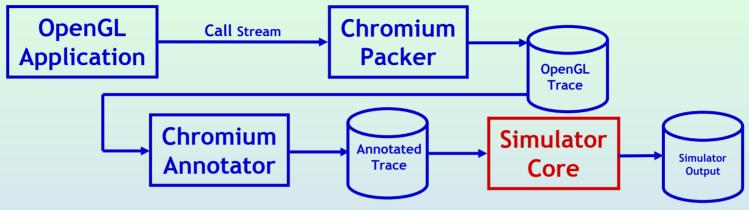
Generating the Input Trace



- Use similar Chromium transformations to gather for each triangle:
 - Number of fragments generated
 - Number of fragments Z-passed
 - Number of fragments on mipmap magnification filter
 - Number of texture accesses
 - Etc.



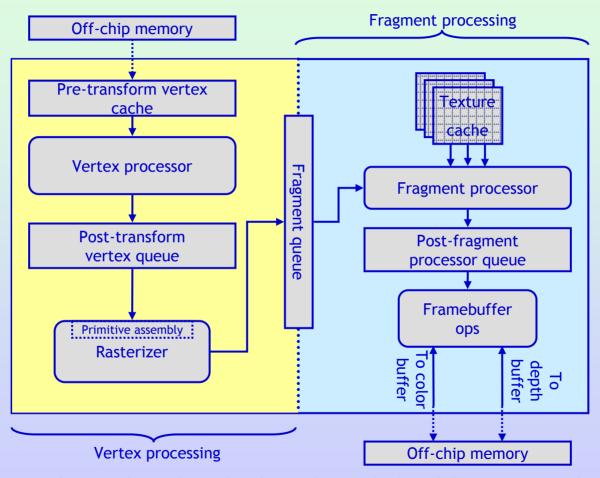
Cycle Timer Model



- Instrumented trace is the input to the simulator core
- Cycle timer is a timing simulation—no computation
 - Already know what events happen
 - Concern is to model when they happen



Architectural Model



- Our results are based on this hypothetical, fixed function pipeline
- Nothing precludes modeling more detail or adding programmability



Modeling Power

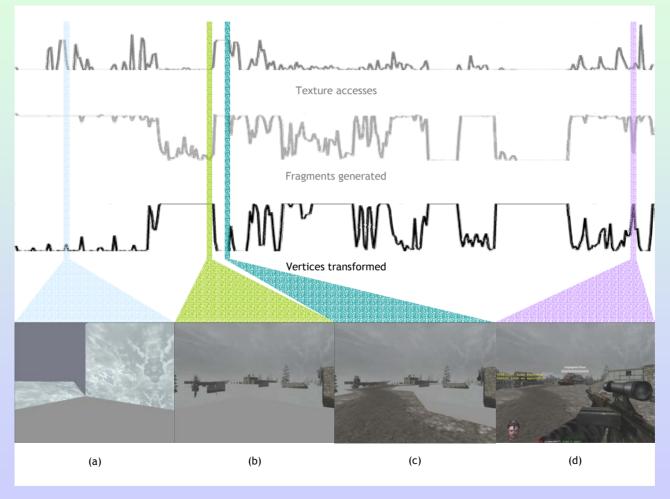
- Qsilver power model based on an industry power model for a high performance CPU
 - Scale appropriately for voltage, frequency, semiconductor process, and bit width
 - Assume data-processing units are microcoded
 - Count events—vertices transformed, fragments created, etc.
 - Multiply by number of primitive operations per event (e.g., adds, multiplies, register/cache/FIFO reads...)
 - Estimates from NVIDIA fixed function pipeline code
 - Multiply by the power cost of a microcoded operation



Applications of Qsilver

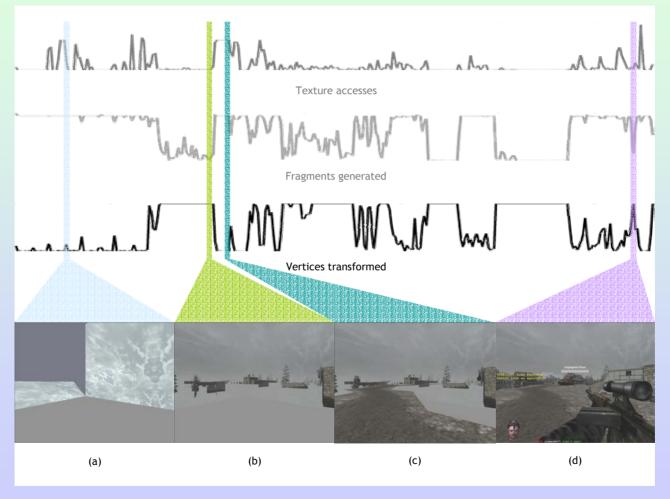
- We demonstrate Qsilver's applicability as a tool for
 - Performance analysis of OpenGL applications
 - Energy efficiency of graphics hardware
- We sketch how Qsilver can serve as a test platform for architectural features
 - For example, Z-min and Z-max culling





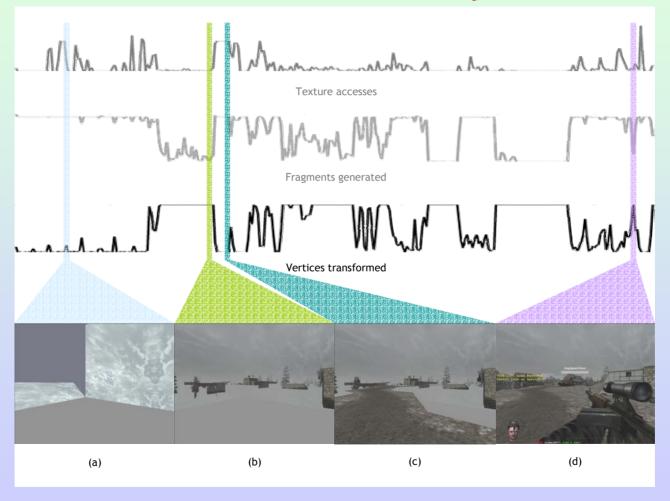
In (a), the game fills in the textured sky-box





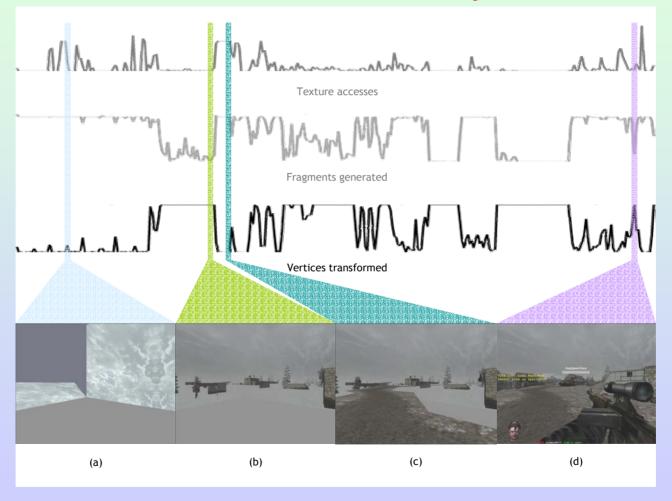
 In (b), the game moves on to details of trees and small buildings





• (c) sees the placement of the road

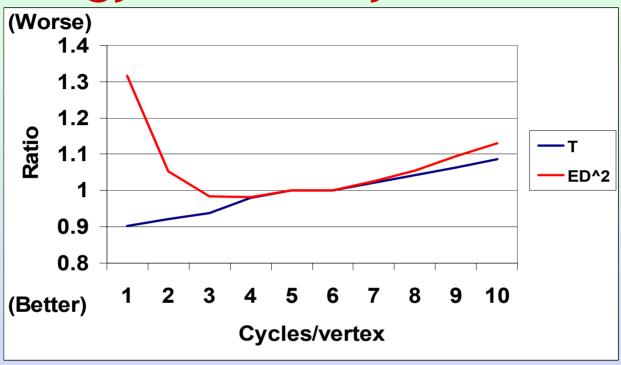




• (d) adds the minutia of the face at lower left



Energy-efficiency Tradeoffs



- Experiment: varying vertex throughput
 - T is performance
 - ED² is energy efficiency metric
 - All normalized to the unpipelined case
- ED² optimum is at 4 cycles/vertex

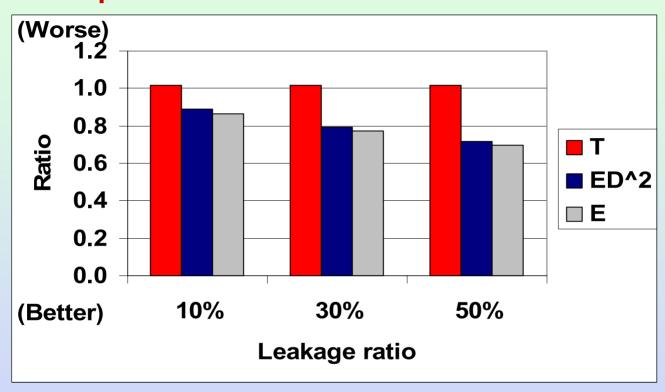


Multiple Clock Domains with DVS

- Multiple independent clocks with dynamically scalable voltage
 - Dynamic Voltage Scaling (DVS) yields cubic reduction in power relative to performance loss ($P \propto V^2 f$)
- Takes advantage of the decoupling fragment queue
 - Pre- and post-fragment queue portions of the chip operate on independent clocks
- DVS setting is controlled by a simple state machine with hysteresis



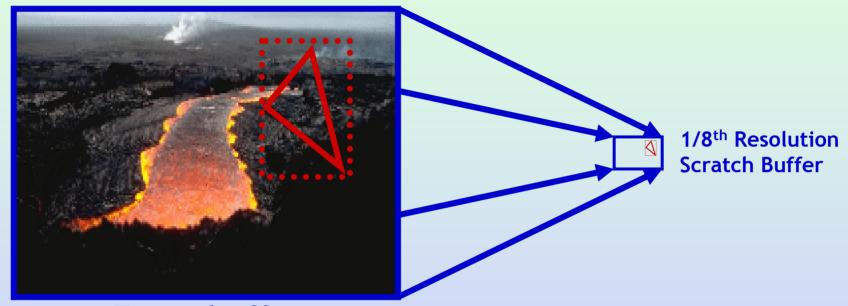
Multiple Clock Domains with DVS



- Experiment: Multiple Clock Domains with DVS
 - T is performance
 - ED2 and E are energy efficiency metrics
 - All normalized to default case with no MCD
- The higher the leakage, the more DVS pays off



Z-Min Culling



Framebuffer

- Render primitive in framebuffer and its filled bounding box in clear scratch buffer
- For each affected pixel in scratch buffer, find new min and max depth of corresponding block in framebuffer
- Re-render primitive in framebuffer with occlusion query and fragment program bound to count only fragments which pass Z-min test



Limitations

- Trace contains only aggregate information
 - No screen-space positions → hard to model:
 - Z-compression
 - Texture cache
 - Etc.
 - Chromium-based annotator makes nonaggregate data difficult to obtain
 - We plan to combine Chromium with Mesa to fill in the missing information



Conclusions

- Qsilver is a new framework for architectural simulation of GPUs
- Qsilver is flexible and highly configurable
- Demonstrated Qsilver's applicability as a tool for performance analysis and energy efficiency study
- Qsilver has the potential to stimulate graphics architecture research



Ongoing and Future Work

Ongoing

- Plug-in architecture with runtime pipeline configuration
- Thermal simulations with *HotSpot*
 - Presented in poster at SIGGRAPH 2004

Future

- Prepare Qsilver for public release
- Iterative refinement
 - Refine power model
 - Pipeline model
- Collect more complete data in the input trace, including screen-space position



http://qsilver.cs.virginia.edu/



Vertex Arrays

- Store vertex arrays in memory
 - Never pass them to the renderer
- Replace accesses into a vertex array with immediate mode calls

```
glEnableClientState(GL_VERTEX_ARRAY);
glVertexPointer(3, GL_FLOAT, 0, verts);
glBegin(GL_TRIANGLES);
glBegin(GL_TRIANGLES);
glArrayElement(6);
glArrayElement(28);
glArrayElement(496);
glEnd();
glBegin(GL_TRIANGLES);
glVertex3fv(verts + 28 * 3);
glVertex3fv(verts + 496 * 3);
glArrayElement(496);
glArrayElement(496);
```



Complex Geometries

- Potentially self occluding and not individual triangles
- Replace with equivalent set of triangles

```
glBegin(GL_TRIANGLE_STRIP);
glVertex3fv(verts);
glVertex3fv(verts + 1);
glVertex3fv(verts + 2);
glVertex3fv(verts + 3);
glVertex3fv(verts + 3);
```



```
glBegin(GL_TRIANGLE);
glVertex3fv(verts);
glVertex3fv(verts + 1);
glVertex3fv(verts + 2);
glEnd();

glBegin(GL_TRIANGLE);
glVertex3fv(verts + 2);
glVertex3fv(verts + 1);
glVertex3fv(verts + 3);
glVertex3fv(verts + 3);
```



Display Lists

- Potentially self occluding
- To handle:
 - Store GL trace in memory
 - Replay it when the list is called
 - Not baked in!
 - The renderer never sees the list as an object
- glCallList invokes the stored code



Counting Texture Accesses

- Check GL state for current texture mode for each triangle
 - Trivial multiplier for texture accesses per fragment
 - If any form of mipmapping is enabled
 - GL_MIN_FILTER and GL_MAG_FILTER require different number of texture lookups!
 - Bind fragment program to determine mipmap level
 - Render the triangle a third time with another occlusion query



Energy-efficiency Tradeoffs

- Highest performance and most energyefficient design points typically not the same
- Use energy-delay-squared (ED²) as energy-efficiency metric
 - Established metric in the low-power design community
 - Smaller ED²→Better energy efficiency
 - Voltage independent



We analyze

 a typical
 series of
 frames
 from Splash
 Damage's
 Enemy
 Territory:
 Escape
 from Castle
 Wolfenstein

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paper28

Submitted to Graphics Hardware 2004